

XAL Status at TRIUMF

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XAL Workshop

MSU-FRIB

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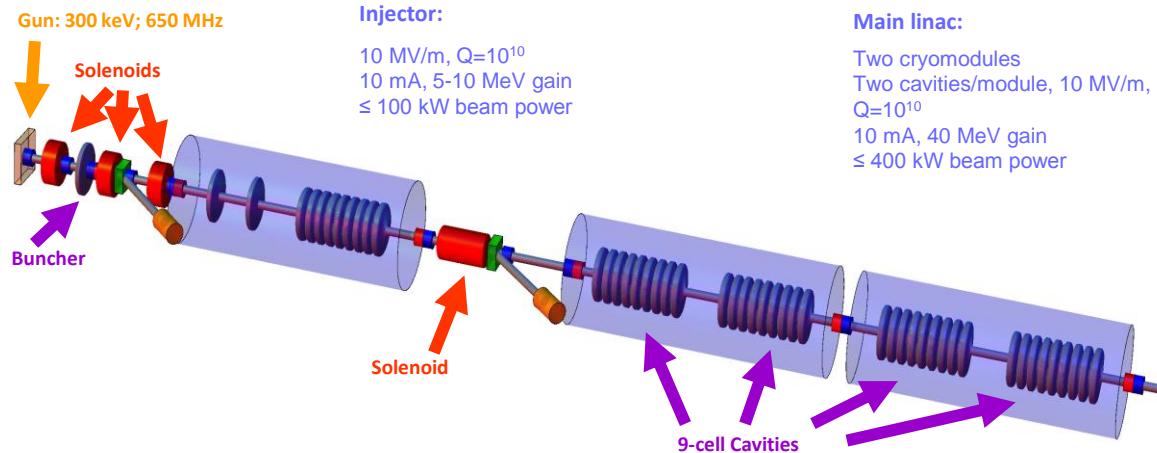
XAL Status at TRIUMF

- XAL identified as the framework for high level applications at TRIUMF
- Initial introduction & exploration – 2009
 - Talk by John Galambos
 - Tutorial by Paul Chu during PAC
 - Evaluation of infrastructure (Database, PV with physical units, modeling,)
- XAL infrastructure on test systems – 2010 (Thanks to help from Paul Chu)
 - Connected to EPICS control of ion source line
 - XML description of ion source line
 - Integration with virtual accelerator
 - Some example applications (automated data acquisition,)
- Low- β model development with intended application on Electron Linac – 2011
 - Deferring database decision (Use XML as test bed to gain experience and define database content needed)
 - Integrated into XAL framework
- Testing and application of low- β model on VECC test facility (not integrated with XAL yet) – 2011-2012
- Model based machine control included as one of Accelerator Division commitments for next 5-Year Plan

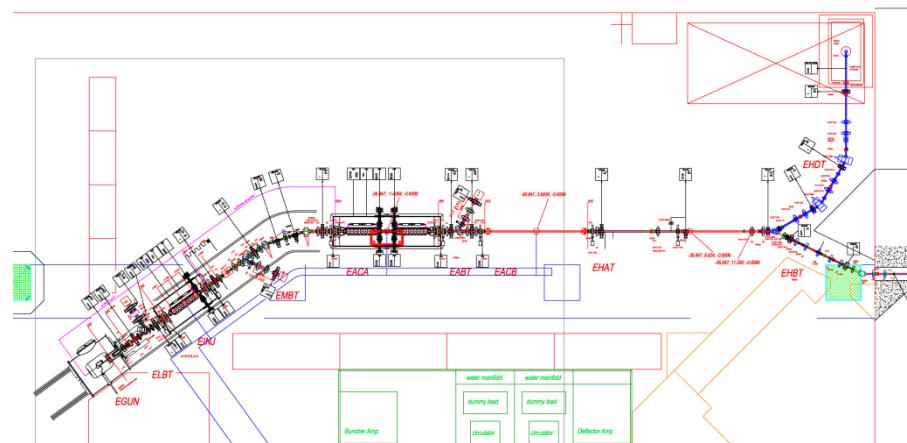
TRIUMF Electron Linac

- 45-75 MeV, 10 mA electron driven photo fission RIB facility
- Injector consists of 300 keV source and SRF acceleration to 10-15 MeV
- Linac accelerates to 45 MeV single pass or 75 MeV after recirculation
- Potential extension to energy recovered FEL at 47 MeV.

Injector and Linac Concept



Layout of Injector and Linac



Layout of 50 MeV Transport to Target



This will be the destination for XAL based control

Low- β Transport Model – to be Integrated with XAL

Motivated by the need to efficiently and correctly model E Linac at front end (300 keV – few MeV)

Time varying fields and Time coordinate are the main focus of this formulation

⇒ Analytical models have not been very successful in modeling RF effects on electrons below a few MeV; Off-design situation is even less tested.

Difficulties In Low- β Modeling by **Analytical** Model

- Velocity changes within cavities
- Non-relativistic dynamics and arrival-time dependence
- Significant momentum transfer between longitudinal and transverse dimensions
- Higher order aberrations in solenoids and in cavities
- Strong chromaticity due to large momentum spread
- Elements inside fringe field of each other due to tight spacing and compact structure
- Non-trivial space charge requiring finer subdivision of elements
- Inadequate mechanism for time-varying elements off design phase
- Over-complex model when all 6 coordinates are needed to describe an element
- Effects on temporal distribution described by transfer matrices based on S-coordinates

A tracking program suffers from none of these difficulties, but it would be too slow to use online.

⇒ Single particle tracking results can be captured in interpolatable and polynomial-expandable data, to be used as an efficient online model with correct physics.

Empirical Model

- Time based formalism
 - Time slip accumulated w.r.t. reference at any S-coordinate
 - Arrival phase at time dependent components
- Compatibility/Interchangeability with XAL modeling scheme
 - Conversion between coordinates
 - Space charge modeling

Index	1	2	3	4	5	6
Coord.	δX (m)	δP_x (MeV/C)	δY (m)	δP_y (MeV/C)	T_{SLIP} (ns)	P_z (MeV/C)

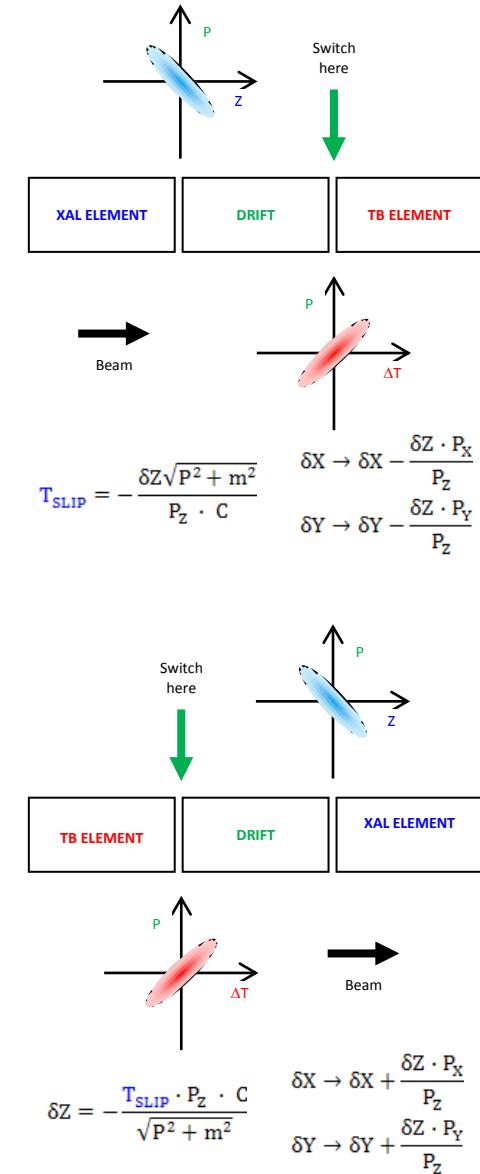
5th coordinate: Cumulative time elapsed relative to design at any given point.

$$T_{SLIP}^N = T_{SLIP}^{N-1} + (\Delta T^N - \Delta T_{DESIGN}^N)$$

At each such element this is translated into relevant unit, such as phase lag relative to design.

$$\Phi^N = \Phi_{DESIGN}^N + \Omega \times T_{SLIP}^{N-1}$$

Design phase Φ_{DES} as well as the interpolation table for cavities are locally referred to the cavity entrance and do not have to be redefined each time they are relocated.



Empirical Model

- Assigning building blocks of this model to XAL infrastructure

Properties of:	Element transport	Design machine state	Actual machine state	Specific input beam
Data	Empirical interpolation table	<ul style="list-style-type: none">• Hardware (B_{DES}, Φ_{DES})• Beam ($\Delta T_{DES}, P_{DES} \dots$)	Hardware setting (amplitude, phase....)	<ul style="list-style-type: none">• Instantaneous (α, β, P)• Cumulative (T_{SLIP})
Implementation	Element attribute	Element attribute	PV	Probe

- Deterministic vs Dynamic propagation & optimization

- Deterministic propagation/optimization
 - Single-particle transport
 - On-design transport
 - Analytical optimization techniques
- Dynamic propagation/optimization
 - Beam distribution needed
 - Off-design transport
 - Empirical, heuristic optimization techniques

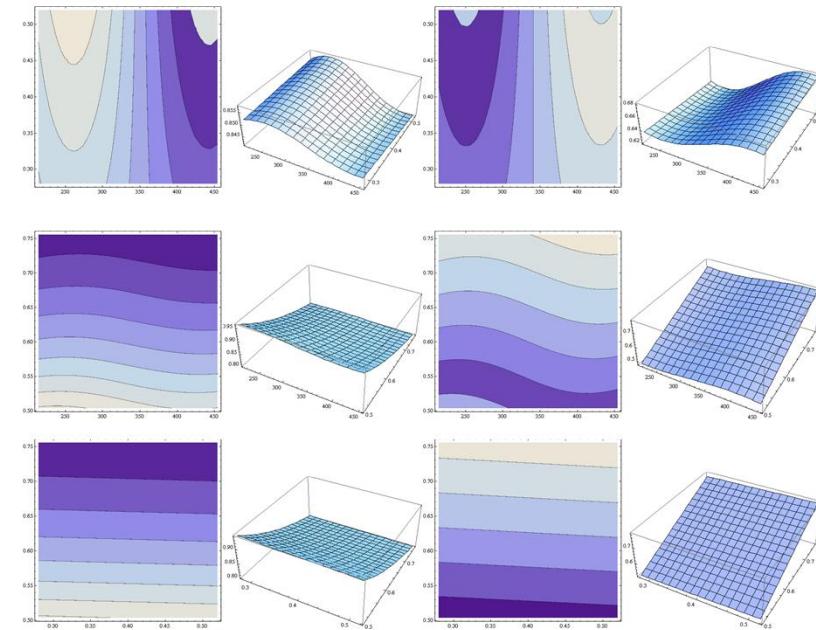
	Single Particle Diag./Control	Phase Space Diag./Control	Beam Propagation – No Space Charge	Beam Propagation – Space Charge
Needed/ Affected Elements	<ul style="list-style-type: none"> Optical elements Steering elements BPM 	<ul style="list-style-type: none"> Optical elements Phase space monitors 	<ul style="list-style-type: none"> Optical elements Phase space monitors Steering elements BPM 	<ul style="list-style-type: none"> Optical elements Phase space monitors
Object Method Used	<ul style="list-style-type: none"> Transfer matrix concatenation Extract higher order transport coefficients 	<ul style="list-style-type: none"> Transfer matrix concatenation Extract higher order transport coefficients 	<ul style="list-style-type: none"> Propagate beam distribution without space charge 	<ul style="list-style-type: none"> Propagate beam distribution with space charge
Design Particle as Reference	<ul style="list-style-type: none"> Mostly (transfer matrices extracted from design trajectory) 	<ul style="list-style-type: none"> Mostly (transfer matrices extracted from design trajectory) 	<ul style="list-style-type: none"> No (Each particle executes own transport) 	<ul style="list-style-type: none"> No (Each particle executes own transport)
Segmented Optical Elements	<ul style="list-style-type: none"> Needed for elements inside fringe fields Effect handled by matrix inversion 	<ul style="list-style-type: none"> No perceivable needs Matrix inversion is sufficient 	<ul style="list-style-type: none"> Needed for elements inside fringe fields Needed for inspection inside optical elements 	<ul style="list-style-type: none"> Needed for compounding space charge effects in subdivided steps
Dimensions	<ul style="list-style-type: none"> Transverse planes only Longitudinal plane only 	<ul style="list-style-type: none"> Transverse planes only Longitudinal plane only 	<ul style="list-style-type: none"> Full 6D or subspace 	<ul style="list-style-type: none"> Full 6D or subspace
Optimization Methods	<ul style="list-style-type: none"> Linear methods Other analytic methods Empirical methods 	<ul style="list-style-type: none"> Linear methods Other analytic methods Empirical methods 	<ul style="list-style-type: none"> Linear methods Other analytic methods Empirical methods 	<ul style="list-style-type: none"> Empirical methods
Examples	<ul style="list-style-type: none"> Misalignment analysis Orbit correction Energy offset diagnosis/correction 	<ul style="list-style-type: none"> Phase space measurement (e.g., linear tomography) Betatron matching 	<ul style="list-style-type: none"> General simulation of beam propagation and experimental procedures 	<ul style="list-style-type: none"> Tomography based on empirical optimization Empirical matching General simulation of experimental procedures

Empirical Model

- Interpolation table and expansion coefficients

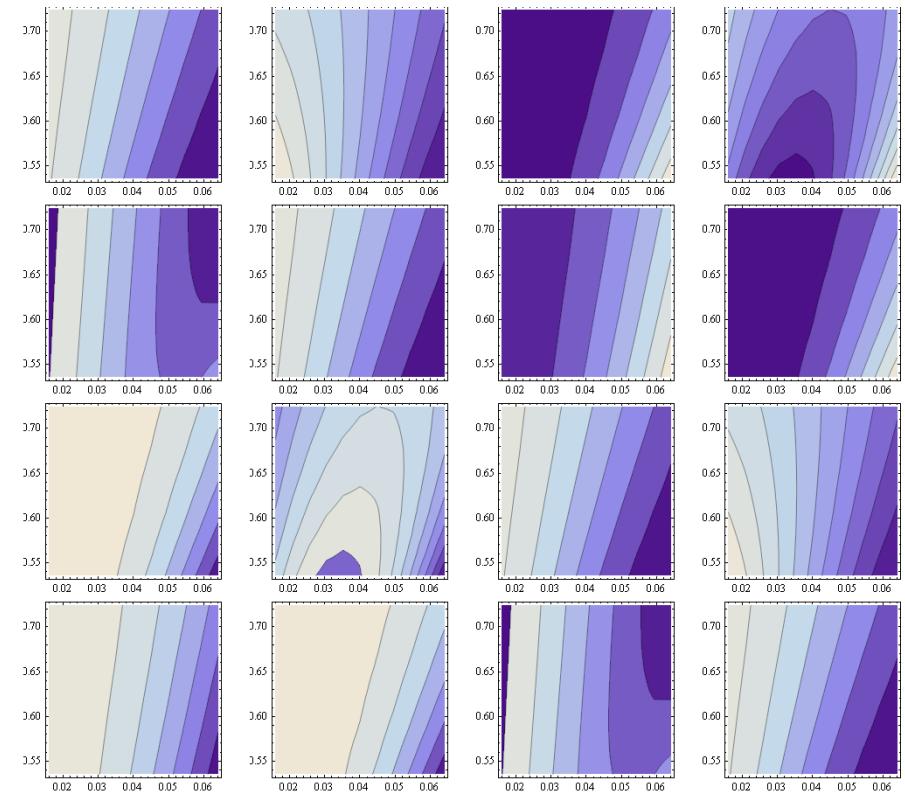
Extract transport properties calculated by tracking program in the form of

- Transit time ΔT , Exit momentum P, and Exit transverse coord. ($\delta X, \delta P_X, \delta Y, \delta P_Y$)
- Expanded in powers of Entry transverse coord. ($\delta X, \delta P_X, \delta Y, \delta P_Y$)
- Interpolated as functions of
 - Phase Φ (e.g., RF)
 - Tuning parameters ($B, \Delta E, \dots$)
 - Entry momentum P.



Contour and 3D plots showing dependence of ΔT (left) & P_{TOTAL} (right) at exit of buncher cavity. Top to bottom:

- $P=0.65$ MeV; Scan over amplitude (MV/m) and phase ($^\circ$)
- Amplitude=0.4 MV/m; Scan over P_{IN} (MeV) and phase ($^\circ$)
- Phase=440 $^\circ$; Scan over P_{IN} (MeV) and amplitude (MV/m)

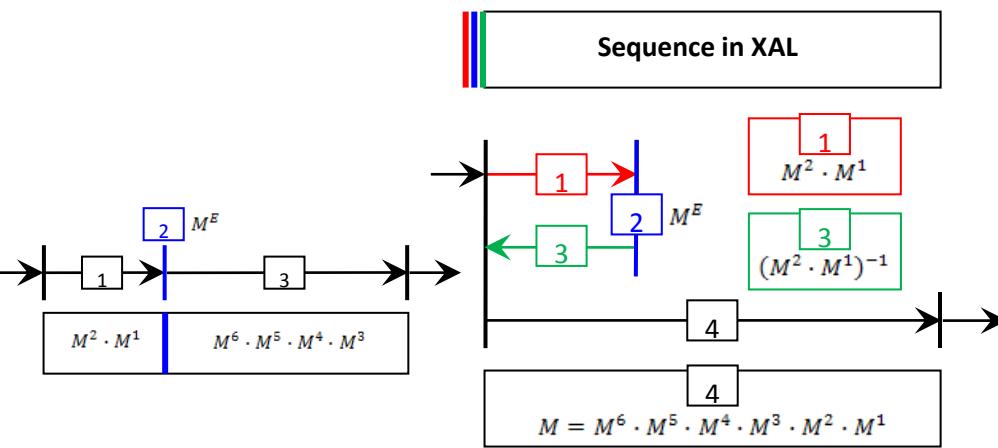
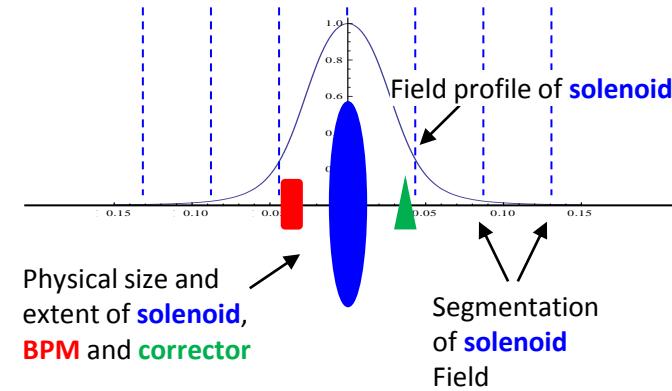


4x4 Contour plots showing dependence of 4x4 transverse transfer matrix coefficients on P_{IN} (MeV) and B field (T).

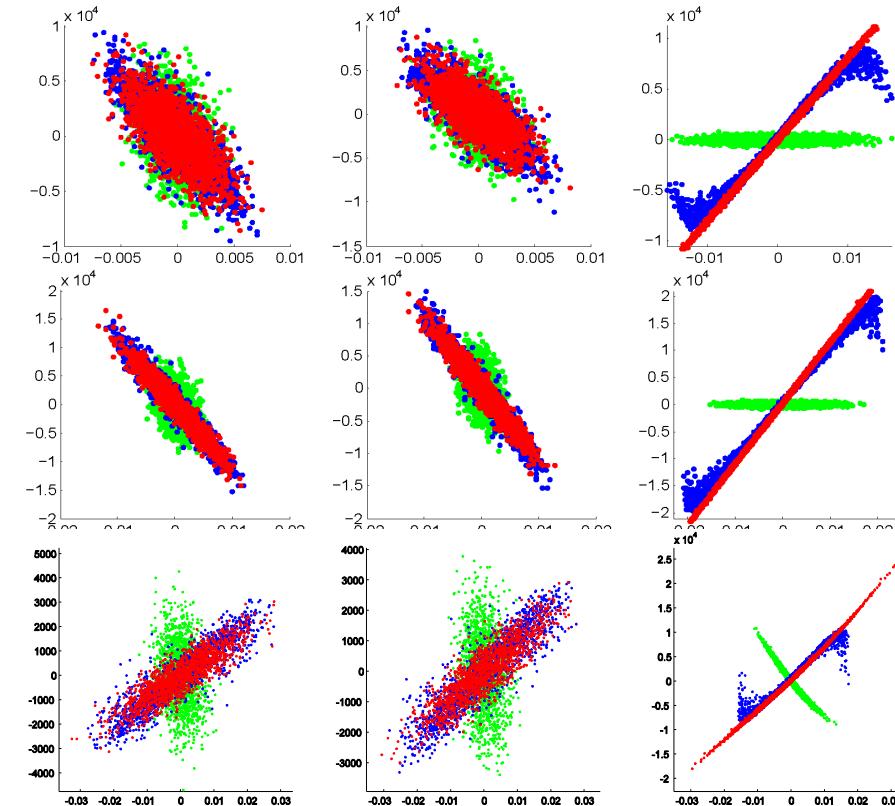
Empirical Model

■ Segmentation of Elements

- Elements in each other's fringe field – Interpolation table constructed for slices
- Space charge modeling using XAL SC algorithm converted to time based



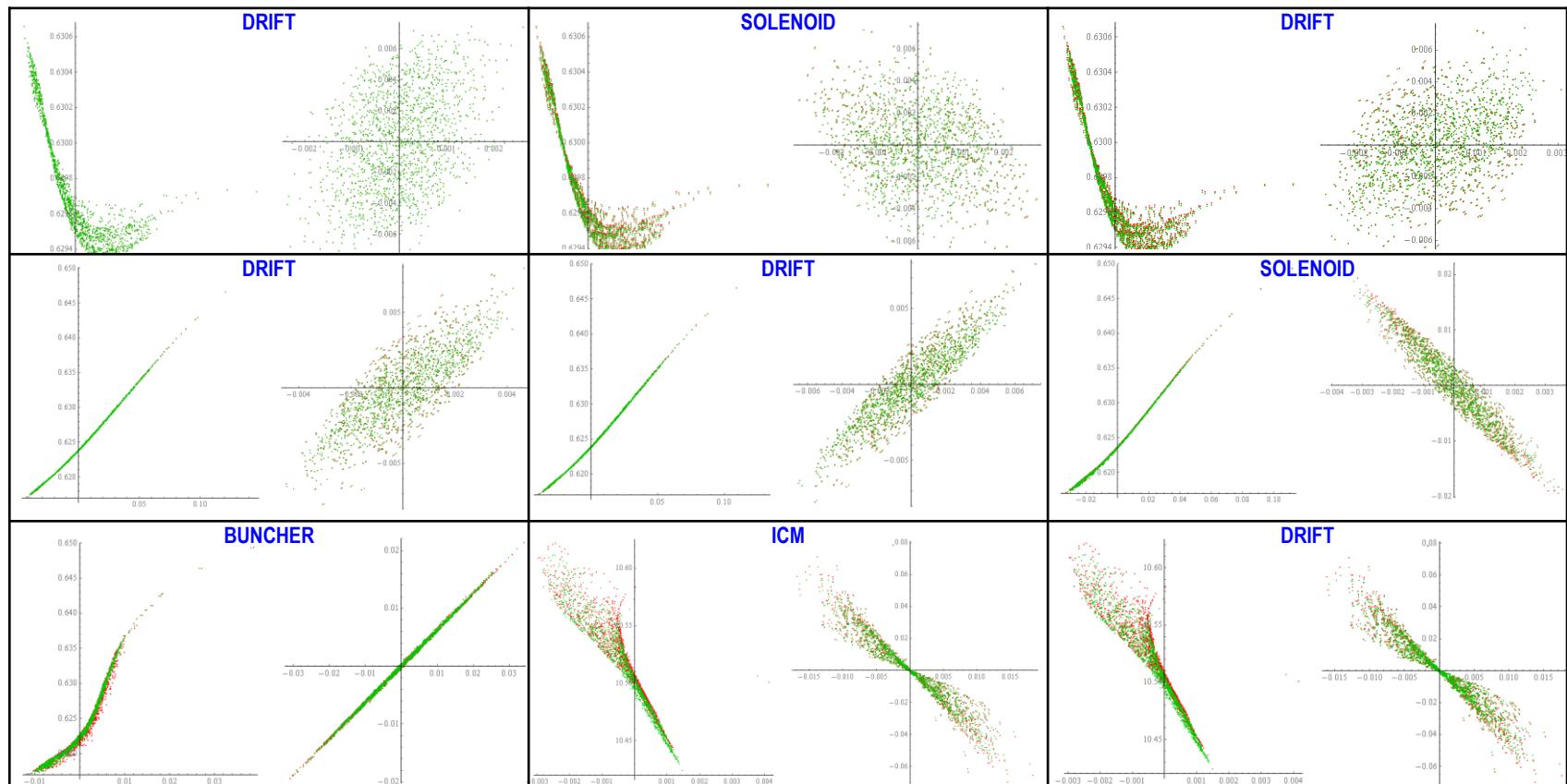
Space charge propagation by time-based empirical model through subdivided segments using equivalent ellipsoidal beam ansatz (red) vs Astra (blue). Green is propagation w/o space charge.
 Left to right: P_x (eV)-X(m), P_y (eV)-Y(m), P_z (eV)-Z(m)
 Top: 100 pC through solenoid.
 Middle: 300 pC through solenoid.
 Bottom: 300 pC through solenoid + cavity + solenoid.



Propagation of Realistic Ensemble Using Empirical Model

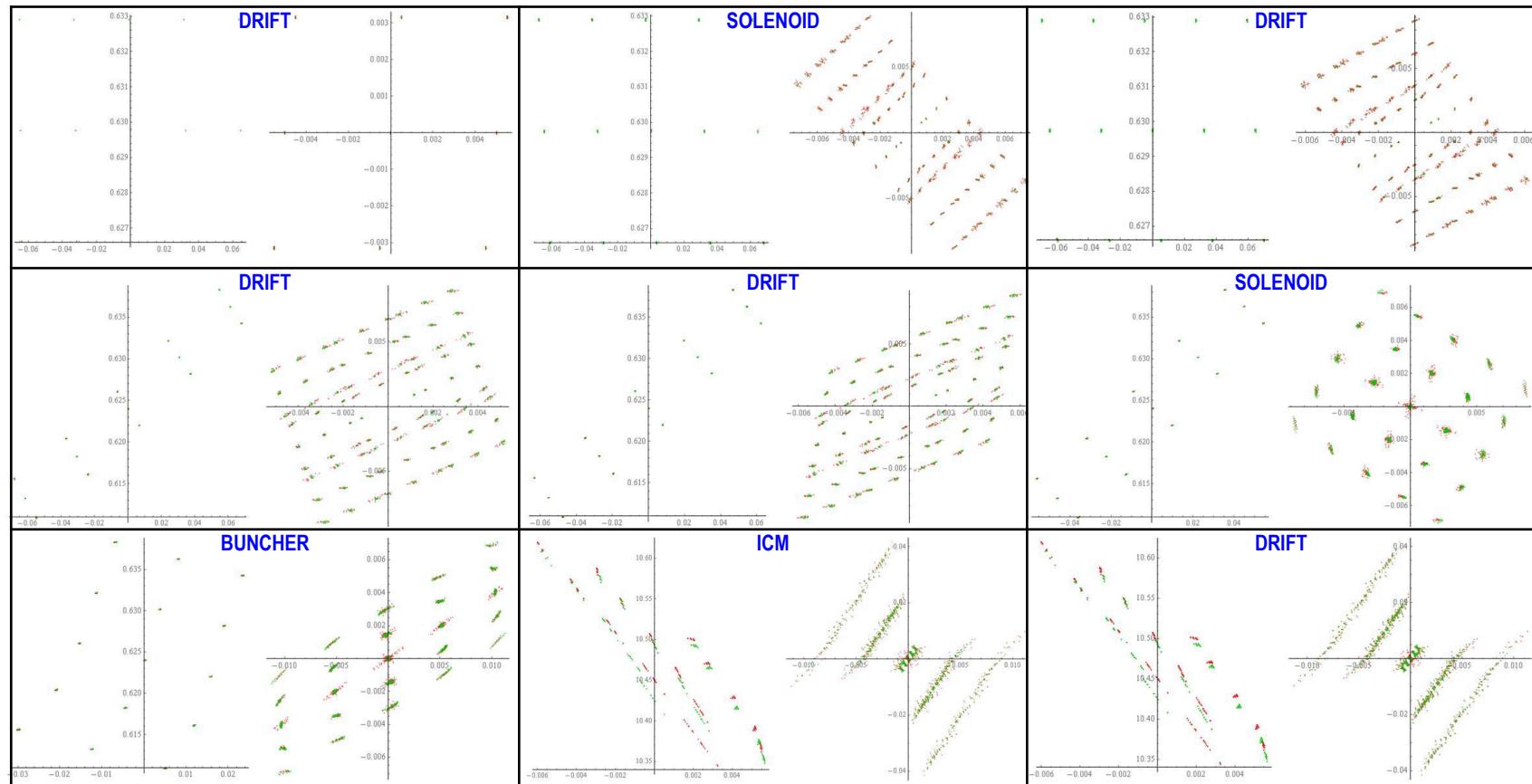
- Test ability to capture complex time dependent low energy dynamics
- Up to 4th order expansion is needed

Beam propagation by Empirical Model (green) & Astra (red) **from 300 keV to 10 MeV through two solenoids, one buncher and one ICM cavity.** All plots: Left: P_Z (MeV/C) vs ΔT (ns); Right: $\delta P_{X/Y}$ (MeV/C) vs $\delta X/Y$ (m). Thermionic gun output is used for initial distribution.



Propagation of 6D Grid Using Empirical Model

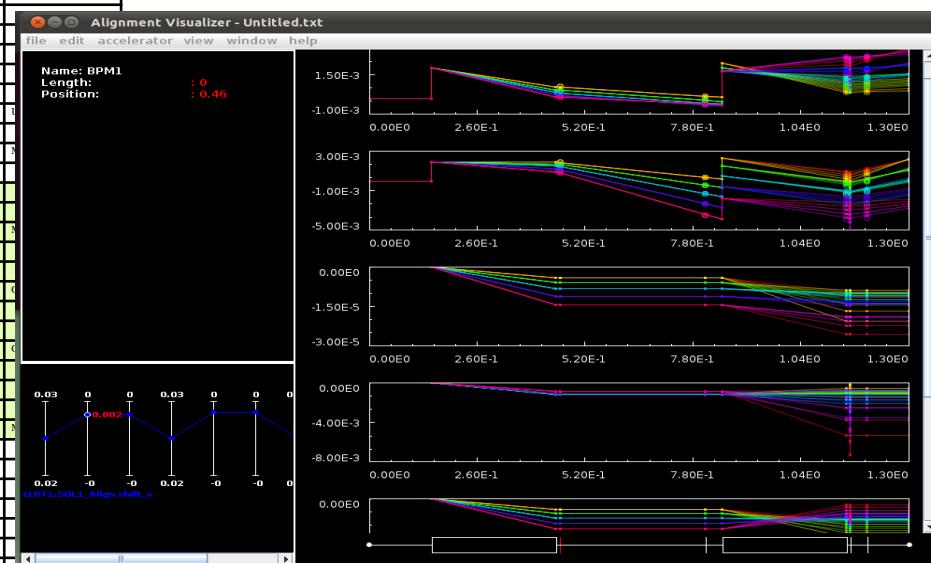
Same comparison between Empirical Model (green) & Astra (red) Large amplitude 6 D grid is used for initial distribution.



Some Applications Were Developed on Virtual Accelerator

Section	Element	Type	Attribute	Value	Comment
ELBT3			Length	1.09381 m	To ICM entrance
			Kinetic Energy	300 keV	
SOL3	Solenoid		Length	0.30 m	Use empirical model
			Position	0.34208 m	
			MaxB	0.67162 m	To dipole entrance
			Attribute	Value	Comment
	ELBT4		Length	0.441/0.450	Mode A/B
			Kinetic Energy	300 keV	
SOL3_R2_B	Sol. Rear 2 Seg. Back Prop.		Length	0.00 m	BUIN
			Position	0.40208 m	RF Cavity
			MaxB	117.7/412.4	Mode A/B
			Attribute	Value	Comment
	XCB1B	DCH	Length	0.00 m	YCB1B
			Position	0.49208 m	Orig. 0.40942 m
			MaxB	173.4/453.4 G	DCV
YCB3A	DCV		Length	0.00 m	
			Position	0.36308 m	BSN: 0.40942 m
SOL3_R2F	Sol. Rear 2 Seg. Fwd. Prop.		Length	0.00 m	SOL2_F2F
			Position	0.326 m	Sol. Front 2 Seg. Fwd. Prop.
			MaxB	173.4/453.4 G	Length
			Attribute	Value	Comment
			Length	0.00 m	BPM1B
			Position	0.326 m	BPM
			MaxB	173.4/453.4 G	Length
SCN3	WS		Length	0.00 m	
			Position	0.326 m	SOL2_F2B
			MaxB	173.4/453.4 G	Sol. Front 2 Seg. Back Prop.
BPM3	BPM		Length	0.00 m	
			Position	0.475038 m	Length
			MaxB	173.4/453.4 G	Position
YCB3B	DCV		Length	0.00 m	SOL2_R2B
			Position	0.626 m	Sol. Rear 2 Seg. Back Prop.
			MaxB	173.4/453.4 G	Length
	XCB2	DCH	Length	0.00 m	
			Position	0.626 m	Back Prop.
			MaxB	384.5/418.7G	Length
	YCB2	DCV	Length	0.00 m	
			Position	0.626 m	Position
			MaxB	173.4/453.4 G	MaxB
SOL2_R2F	Sol. Rear 2 Seg. Fwd. Prop.		Length	0.00 m	
			Position	0.626 m	Length
			MaxB	173.4/453.4 G	Position
			Attribute	Value	Comment
			Length	0.00 m	SOL1_R2F
			Position	0.4184 m	Sol. Rear 2 Seg. Fwd. Prop.
			MaxB	384.5/418.7G	Length
SCN1A	WS		Length	0.00 m	
			Position	0.41158 m	Position
			MaxB	384.5/418.7G	MaxB
BPM1A	BPM		Length	0.00 m	
			Position	0.491 m	Length
			MaxB	384.5/418.7G	Position

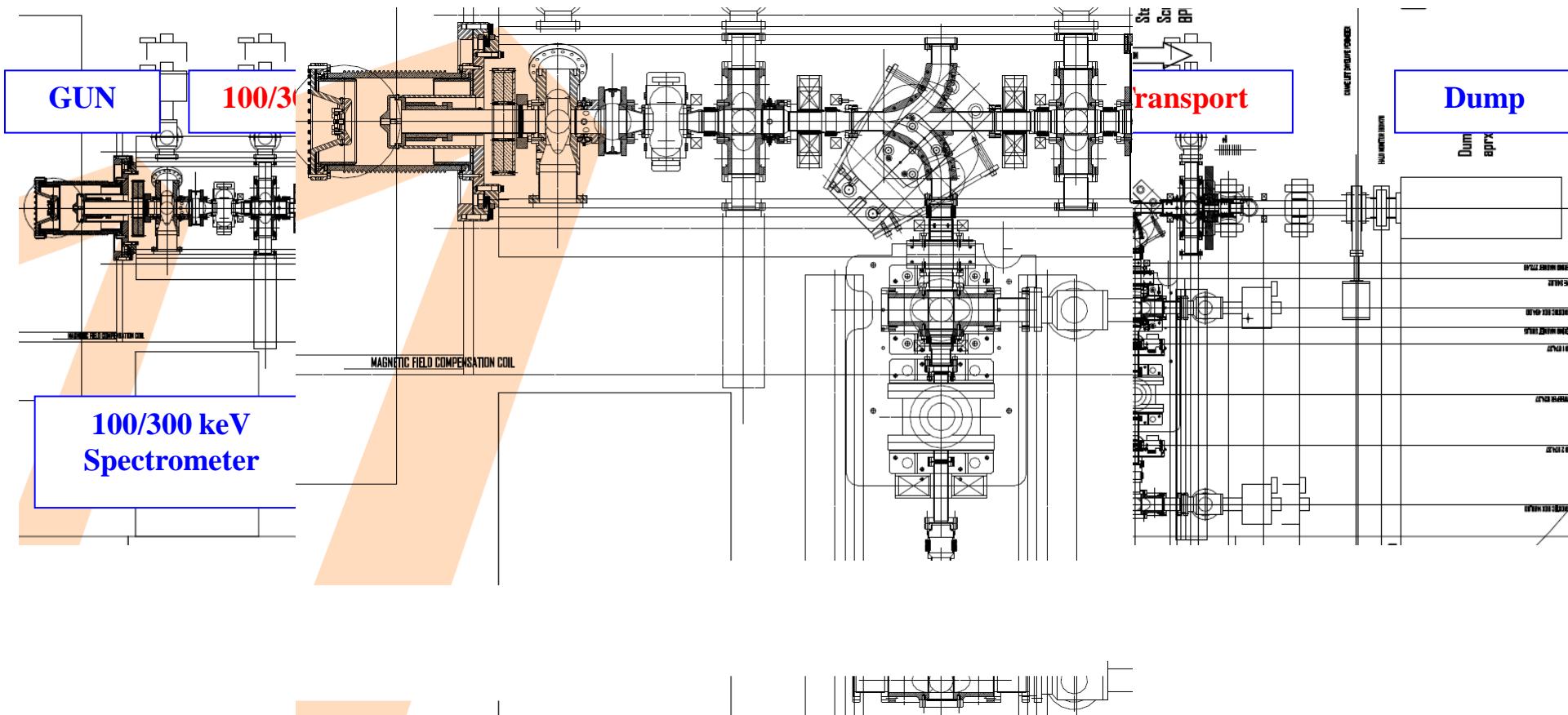
Section	Element	Type	Attribute	Value	Comment
ELBT4			Length	1.280 m	To ICM exit
			Kinetic Energy	300 keV	Input
	ICM	RF Cavity	Length	1.280 m	Use empirical model
			Position	0.640 m	
			MaxE	20/20 MV/m	Mode A/B
			Phase	260.1/258.8°	Mode A/B
ELBT5			Length	1.0 m	To dump
			Kinetic Energy	10 MeV	
ELBTD			Length	1.5 m	To spectrometer dump
			Kinetic Energy	300 keV	
	DB0	DH	Length	0.2356 m	
			Position	0.1178 m	
			Bend Angle	90°	
			dipoleEntrR	0°	
			atAngle		
			dipoleExitR	0°	
			otAngle		



A demo high level application program built on XAL framework using low energy empirical model to perform solenoid misalignment analysis

VECC Test Facility – Prototype of E Linac Front End

Full Complement



Beam Based Characterization of VECC

Purpose

- Understand & Debug VECC longitudinal & transverse transport – Resolve discrepancy / Update model
- Enable translation of beam phase space between any two points
- Provide basis for model based high level diagnostic & control algorithms

6D Transport

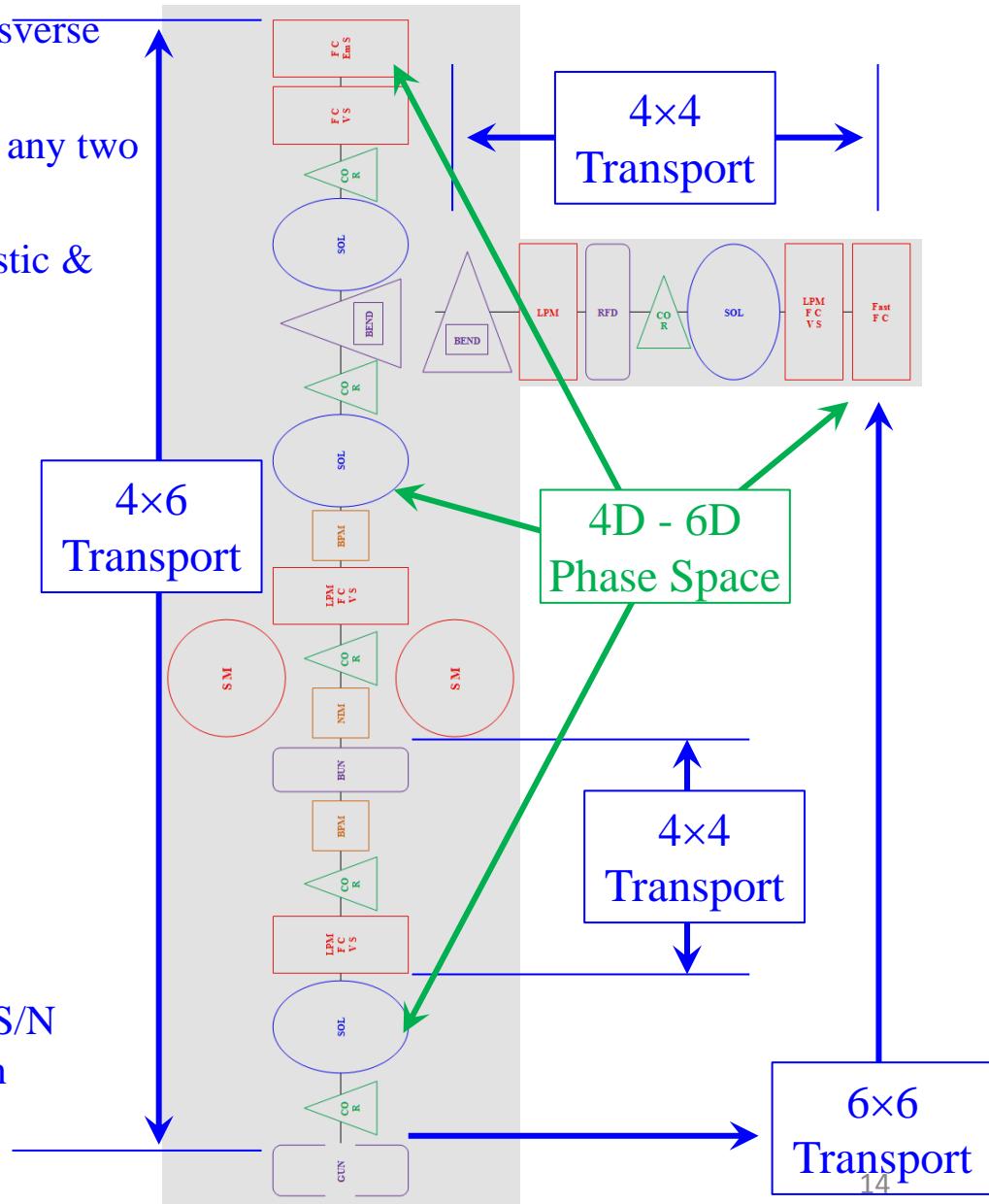
- Between key locations
- Across key components
- Amplitude dependence
- Critical to phase space determination

6D Beam Phase Space

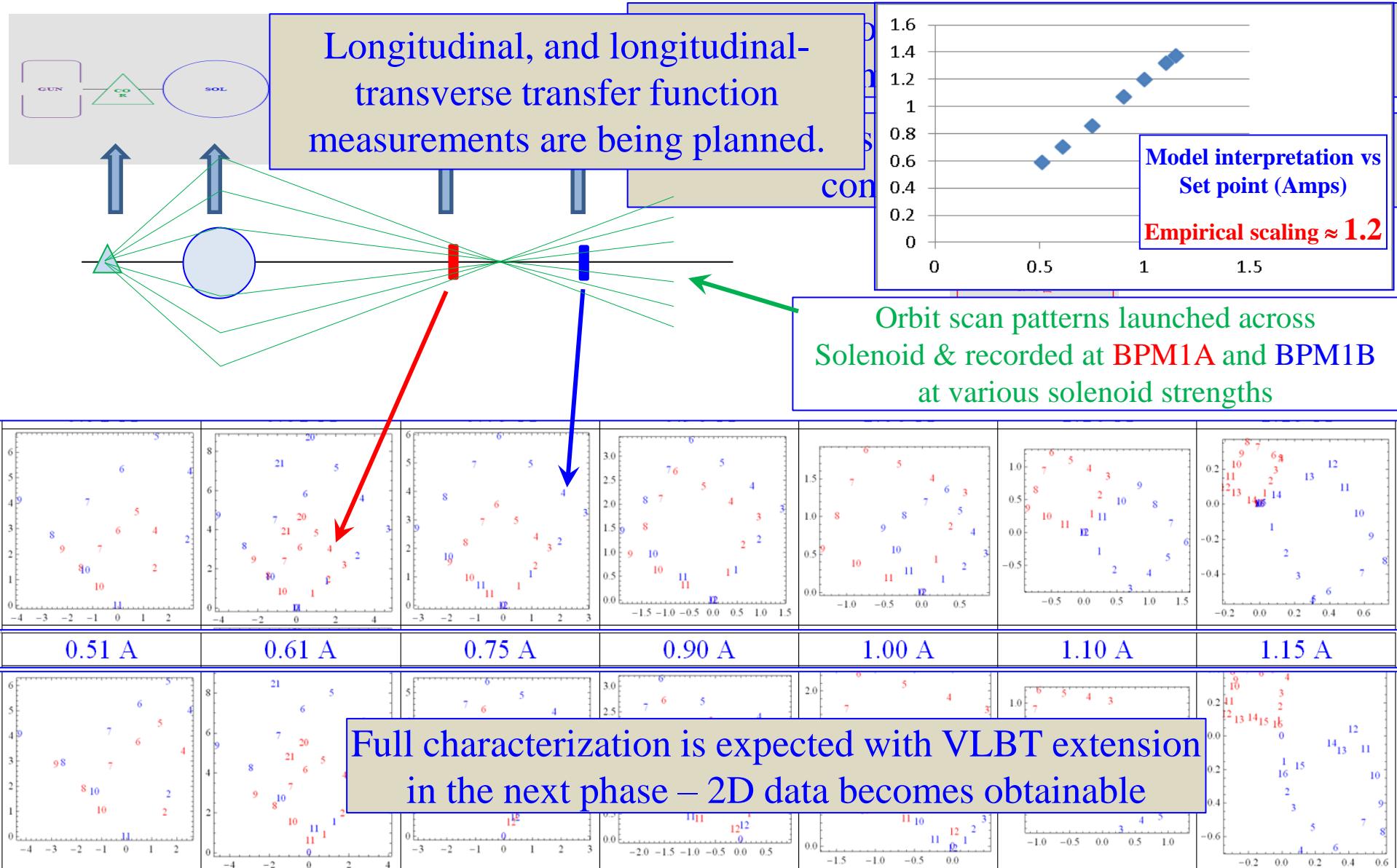
- At key locations
- Consistency with 6D transport
- Consistency among different methods
- Dependence on space charge

Offline Feasibility Studies

- GPT simulation - Configuration robustness and S/N
- Empirical transport model – Fast exp. simulation
- Special machine tune for measurements

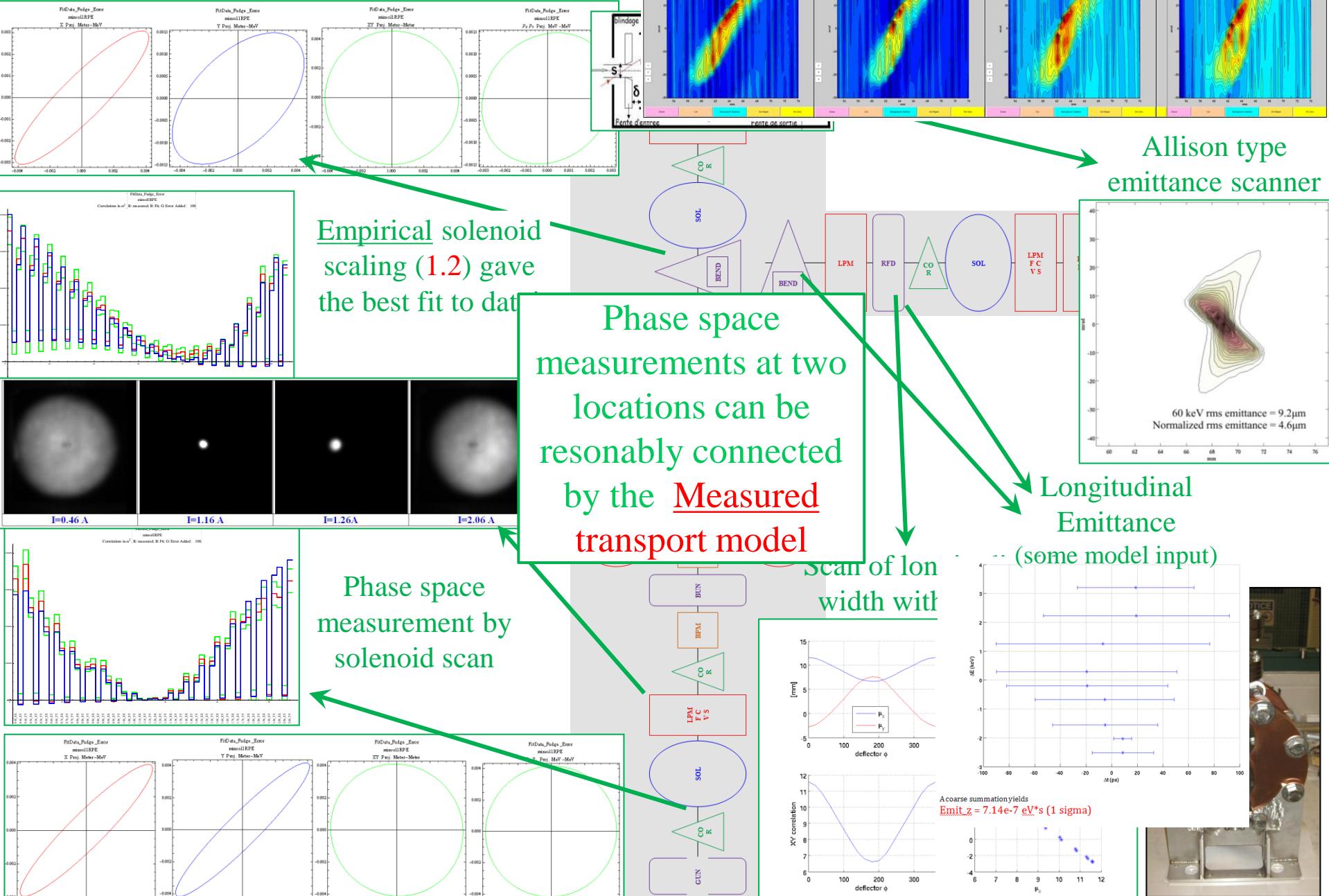


Transport Model Measurement & Calibration



Top: Model interpretation of data; Bottom: Data

Beam Phase Space Measurements



Summary

- XAL identified as the framework for TRIUMF E Linac
- Commitment from Accelerator Division for model based control
- Complementary low- β model developed and being beam tested
- Major infrastructure work awaits (Database, PV with physical units....)
- Ambitious plan for comprehensive high level model based diagnostic and control – However resource needs be identified.
- Help/collaboration from community would be key.